## **BLITZ**Sensor



BS-FN150-M-D6EC is an inertial navigation system (INS) based on fiber-optic gyroscopes

- Fiber-optic gyroscopes and three MEMS acceleromters
- Digital output

| Item Purpose |   | Indicators                             | Remark                               |
|--------------|---|--|--------------------------------------|
|              | Measuring range                         | -500°/s $\sim$ +500°/s                 |                                      |
|              | Zero-bias residual                      | -0.25°/h $\sim$ +0.25°/h               |                                      |
|              | Random walk                             | 0.05 °/h                               |                                      |
| GYRO         | Zero bias stability at                  | $\leq 0.1^{\circ}/h$ (1 $\sigma$ )     | 10 seconds smoothing, 1H test result |
|              | room temperature                        |  |                                      |
|              | Zero bias stability at full temperature | $\leq 0.15^{\circ}/h$ (1 $\sigma$ )    | 10 seconds smoothing, 1H test result |
|              | Normal-temperature                      | ≤0.1°/h (1σ)                           | Statistics of 6 test data            |
|              | zero-bias repeatability                 |  |                                      |
|              | Zero-bias repeatability at              | $\leq\!\!0.15^{\circ}\!/\!h~(1\sigma)$ | Take 2 zero-bias data at full        |
|              | full temperature                        |  | temperature, high temperature, low   |
|              |   |  | temperature and normal temperature   |
|              |   |  | respectively                         |
|              | Scale factor nonlinearity               | ≤30ppm                                 | Full temperature and constant        |
|              |   |  | temperature                          |
|              | Scale factor repeatability              | $\leq 30 ppm (1\sigma)$                | Full temperature and constant        |
|              |   |  | temperature                          |
|              | Gyro start time                         | ≤5s                                    |                                      |
|              | Gyro bandwidth                          | 300Hz                                  | Design assurance, batch testing      |
|              | Installation error residual             | ≤80"                                   |                                      |
|              | of three-axis gyroscope                 |  |                                      |

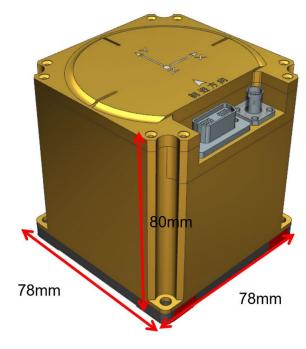
## BLITZSensor

|     | Item Purpose                                     | Indicators                  | Remark   |
|-----|--|-----------------------------|--|
| ACC | Measuring range                                  | -20g $\sim$ +20g            | Design and selection guarantee   |
|     | Scale factor nonlinearity                        | ≤300ppm                     | Design and selection guarantee   |
|     | Zero bias stability at full temperature          | $\leq 100$ ug (1 $\sigma$ ) | 10 seconds smoothing, 1H test result   |
|     | Zero-bias repeatability at<br>full temperature   | $\leq 100$ ug (1 $\sigma$ ) | Take 2 zero-bias data at full temperature,<br>high temperature, low temperature and<br>normal temperature respectively |
|     | Scale factor repeatability                       | $\leq 100 ppm (1\sigma)$    | Design and selection guarantee   |
|     | Random walk                                      | $\leq 0.02 m/s/h^{1/2}$     |  |
|     | Add up the starting time                         | ≤5s                         |  |
|     | Triaxial addition<br>installation error residual | ≤80"                        |  |

| Item Purpose |  | Indicators | Remark                                 |
|--------------|--|------------|--|
|              | Static self-north seeking time           | ≤5min      |  |
| Alignment    | Heading Angle<br>Alignment Repeatability | ≤0.2°      | 1σ                                     |
| accuracy     | Pitch Alignment<br>Repeatability         | ≤0.05°     | 1σ                                     |
|              | Roll Angle Alignment<br>Repeatability    | ≤0.05°     | 1σ                                     |
|              | North-seeking mode                       | Optional   | Shaking base alignment can be achieved |

| Item Purpose                       |                                      | Indicators            | Remark                          |  |  |  |  |
|------------------------------------|--------------------------------------|-----------------------|---------------------------------|--|--|--|--|
| Inertial<br>navigation<br>accuracy | Accuracy of course angle maintenance | ≤0.15°/h              |                                 |  |  |  |  |
|                                    | Pitch Angle<br>Holding Accuracy      | ≤0.05°/h              |                                 |  |  |  |  |
|                                    | Accuracy of roll angle maintenance   | $\leq 0.05^{\circ}/h$ |                                 |  |  |  |  |
|                                    | Inertial<br>positioning<br>accuracy  | ≤10m (300s, 3km)      | CEP, Carrier Constraint         |  |  |  |  |
|                                    | Inertial<br>positioning<br>accuracy  | ≤2000m (15min)        | Airborne, error<br>peak-to-peak |  |  |  |  |

## **BLITZ**Sensor



安装尺寸: 69.5\*69.5 (4\*Ø4.5)



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